

Non-existence of the global solution of initial boundary value problem for the incompressible two-velocity medium equation

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Abstract. An initial boundary value problem for systems of viscous two-fluid media with equilibrium of pressure phases is considered. Using the test function method proposed by S.I. Pohozaev and E. Mitidieri, the effect of boundary and initial conditions on the appearance, time and rate of destruction of solutions of this problem is investigated.

Keywords: Two-velocity hydrodynamics, initial boundary value problem, destruction.

1. Introduction

The fundamental problem of modern hydrodynamics, inherited from classical fluid mechanics, remains the study of the dynamics and interaction of vortex structures. According to the figurative expression in Saffman's book [1], vortexes are “muscles and veins of hydrodynamics”. Without idea of the mechanisms that determine their behavior, it is impossible to achieve progress in constructing dynamic models of turbulence, in solving stability, and control flow problems, in improving the wing aerodynamics and in developing many other sections of the hydrodynamic theory and technical applications.

One of the most important issues in the theory of nonlinear differential equations is the question of uniqueness, existence, and destruction of solutions. If there is a local solvability, a smooth solution to the evolution equations may not exist on the entire time axis and may collapse in finite time. Theoretical studies of the destruction phenomenon of the Cauchy problems for hydrodynamics models have begun since the last century [2, 3]. However, from a practical point of view, the formulation of a problem in an unbounded domain is complicated, and in the numerical simulation we have to consider the initial boundary value problem by adding the boundary conditions [4]. In this paper, we raise the question of the local solvability for systems of equations of a two-fluid medium with the equilibrium pressure phases and demonstrate the ability of the method offered by S.I. Pohozaev and E. Mitidieri to obtain sufficient conditions of the global unsolvability of possible supplementary problems for systems of the form [5–7]:

$$\operatorname{div}(\rho \mathbf{v}) = 0, \quad \operatorname{div}(\tilde{\rho} \tilde{\mathbf{v}}) = 0, \quad (1)$$

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v}, \nabla) \mathbf{v} = -\frac{\nabla p}{\bar{\rho}} + \nu \Delta \mathbf{v} + \frac{\tilde{\rho}}{2\bar{\rho}} \nabla(\tilde{\mathbf{v}} - \mathbf{v})^2, \quad (2)$$

$$\frac{\partial \tilde{\mathbf{v}}}{\partial t} + (\tilde{\mathbf{v}}, \nabla) \tilde{\mathbf{v}} = -\frac{\nabla p}{\bar{\rho}} + \tilde{\nu} \Delta \tilde{\mathbf{v}} - \frac{\rho}{2\bar{\rho}} \nabla(\tilde{\mathbf{v}} - \mathbf{v})^2, \quad (3)$$

where $\tilde{\mathbf{v}}$ and \mathbf{v} are the velocity vectors of the subsystems of the components of the two-velocity continuum with the respective partial densities $\tilde{\rho}$ and ρ , ν , and $\tilde{\nu}$ are the respective kinematic viscosities, $\bar{\rho} = \tilde{\rho} + \rho$ is the total density of two-velocity continuum; $p = p(\bar{\rho}, (\tilde{\mathbf{v}} - \mathbf{v})^2)$ is the equation of state of the two-velocity continuum.

Systems of this type arise when describing the motion of mutual penetration of a less viscous fluid through a more viscous medium, as a kind of filtering process [5, 6]. Or by analogy with the Navier–Stokes equations, this model can be called a two-velocity Navier–Stokes equation or the two-velocity hydrodynamics.

To study the destruction of solutions, we use the method developed by S.I. Pohozaev, E. Mitidieri and V.A. Galaktionov and called the method of test functions, or the method of nonlinear capacity. For the detailed acquaintance with the possibilities of this method we refer to [8–13]. In particular, the use of the test functions of a special form in the hydrodynamics is discussed in [14–17].

2. Destruction of the solution to a system of the two-velocity hydrodynamics equations with one pressure

For the system of equations (1)–(3) in the cylindrical domain $\Omega = [0, R] \times [0, 2\pi] \times [0, L]$, we investigate the following initial boundary value problem with the following initial conditions

$$\tilde{\mathbf{v}}|_{t=0} = \tilde{\mathbf{v}}_0(\mathbf{x}), \quad \mathbf{v}|_{t=0} = \mathbf{v}_0(\mathbf{x}), \quad (4)$$

and the boundary conditions

$$\begin{aligned} \tilde{v}_z(r, \varphi, 0) = 0, \quad \tilde{v}_r(R, \varphi, z) = \tilde{v}_r(0, \varphi, z) = 0, \\ - \int_0^{2\pi} \int_0^R \left(\tilde{v}_z(r, \varphi, L) + L \frac{\partial \tilde{v}_z}{\partial z}(r, \varphi, 0) \right) d\varphi dr + \\ \int_0^{2\pi} \int_0^L (z - L) R \frac{\partial \tilde{v}_z}{\partial r}(R, \varphi, z) d\varphi dz = \tilde{h}(t), \end{aligned} \quad (5)$$

$$\begin{aligned}
v_z(r, \varphi, 0) = 0, \quad v_r(R, \varphi, z) = v_r(0, \varphi, z) = 0, \\
- \int_0^{2\pi} \int_0^R \left(v_z(r, \varphi, L) + L \frac{\partial v_z}{\partial z}(r, \varphi, 0) \right) d\varphi dr + \\
\int_0^{2\pi} \int_0^L (z-L) R \frac{\partial v_z}{\partial r}(R, \varphi, z) d\varphi dz = h(t), \quad (6)
\end{aligned}$$

where $h(t), \tilde{h}(t) \in C[0, \infty)$.

Let us choose the test function

$$\mathbf{u} = (0, 0, z - L), \quad z \in [0, L].$$

By virtue of boundary conditions (5), (6) in the class $\mathbf{v}(\mathbf{x}, t), \tilde{\mathbf{v}}(\mathbf{x}, t) \in C^1((0, T]; C^2(\bar{\Omega}) \times C^2(\bar{\Omega}) \times C^2(\bar{\Omega}))$, we have the following relations:

$$\begin{aligned}
\int_{\Omega} \Delta \mathbf{v} \mathbf{u} \, d\mathbf{x} &= \int_{\Omega} \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \varphi^2} + \frac{\partial^2 v_z}{\partial z^2} \right) (z-L) r \, dr \, d\varphi \, dz \\
&= \int_0^{2\pi} \int_0^L r \frac{\partial v_z}{\partial r} \Big|_0^R (z-L) \, d\varphi \, dz + \\
&\quad \int_0^R \int_0^L \frac{1}{r} \frac{\partial v_z}{\partial \varphi} \Big|_0^{2\pi} (z-L) \, dr \, dz + \\
&\quad \int_0^{2\pi} \int_0^R \left((z-L) \frac{\partial v_z}{\partial z} - v_z \right) \Big|_0^L d\varphi \, dr \\
&= \int_0^{2\pi} \int_0^L R \frac{\partial v_z}{\partial r}(R, \varphi, z) (z-L) \, d\varphi \, dz - \\
&\quad \int_0^{2\pi} \int_0^R \left(v_z(r, \varphi, L) + L \frac{\partial v_z}{\partial z}(r, \varphi, 0) \right) d\varphi \, dr = h(t), \quad (7)
\end{aligned}$$

$$\begin{aligned}
\int_{\Omega} (\mathbf{v}, \nabla) \mathbf{v} \mathbf{u} \, d\mathbf{x} &= \int_{\Omega} \left(v_r \frac{\partial v_z}{\partial r} + \frac{1}{r} v_{\varphi} \frac{\partial v_z}{\partial \varphi} + v_z \frac{\partial v_z}{\partial z} \right) (z-L) r \, dr \, d\varphi \, dz \\
&= \int_{\Omega} \left(\frac{\partial}{\partial r} (r v_r v_z) + \frac{\partial}{\partial \varphi} (v_{\varphi} v_z) + r v_z \frac{\partial v_z}{\partial z} \right) (z-L) \, dr \, d\varphi \, dz - \\
&\quad \int_{\Omega} \left(\frac{\partial (r v_r)}{\partial r} + \frac{\partial v_{\varphi}}{\partial \varphi} \right) v_z (z-L) \, dr \, d\varphi \, dz \\
&= \int_0^{2\pi} \int_0^L r v_r v_z \Big|_0^R (z-L) \, d\varphi \, dz + \int_0^R \int_0^L v_{\varphi} v_z \Big|_0^{2\pi} (z-L) \, dr \, dz + \\
&\quad \int_{\Omega} \left(\frac{\partial v_z}{\partial z} - \frac{1}{r} \left(\frac{\partial (r v_r)}{\partial r} + \frac{\partial v_{\varphi}}{\partial \varphi} \right) \right) v_z (z-L) r \, dr \, d\varphi \, dz \\
&= \int_0^{2\pi} \int_0^R r v_z^2 (z-L) \Big|_0^L \, dr \, d\varphi - \int_{\Omega} v_z^2 r \, dr \, d\varphi \, dz \\
&= - \int_{\Omega} v_z^2 r \, dr \, d\varphi \, dz. \quad (8)
\end{aligned}$$

Here we used the equality $\operatorname{div} \mathbf{v} = 0$ implying

$$\frac{\partial(rv_r)}{\partial r} + \frac{\partial v_\varphi}{\partial \varphi} = -r \frac{\partial v_z}{\partial z}.$$

We multiply both sides of equation (2) by ρ , equation (3) by $\tilde{\rho}$ and, as a result, obtain the law of conservation of momentum

$$\frac{\partial(\rho \mathbf{v} + \tilde{\rho} \tilde{\mathbf{v}})}{\partial t} + \rho(\mathbf{v}, \nabla) \mathbf{v} + \tilde{\rho}(\tilde{\mathbf{v}}, \nabla) \tilde{\mathbf{v}} = -\nabla p + \Delta(\rho \mathbf{v} + \tilde{\rho} \tilde{\mathbf{v}}). \quad (9)$$

Denote $P = p + \frac{\rho}{2}(\tilde{\mathbf{v}} - \mathbf{v})^2$. In terms of $\tilde{\mathbf{v}}$ and P , equation (3) has the form

$$\frac{\partial \tilde{\mathbf{v}}}{\partial t} + (\tilde{\mathbf{v}}, \nabla) \tilde{\mathbf{v}} = -\frac{\nabla P}{\tilde{\rho}} + \tilde{\nu} \Delta \tilde{\mathbf{v}}. \quad (10)$$

Taking into account the inequality

$$\begin{aligned} -\int_{\Omega} \nabla p \mathbf{u} \, d\mathbf{x} &= \int_{\Omega} \frac{\partial p}{\partial z} (L - z) \, d\mathbf{x} = \int_{\Omega} p \, d\mathbf{x} + \int_0^R \int_0^{2\pi} (L - z)p|_0^L r \, dr \, d\varphi \\ &\geq -\int_0^R \int_0^{2\pi} r L p(r, \varphi, 0) \, dr \, d\varphi \equiv g(t), \end{aligned}$$

where $\int_{\Omega} p \, d\mathbf{x} \geq 0$, $g(t) \in C[0, \infty)$, multiplying both sides of equations (9) and (10) by the test function, and using relations (7), (8), we obtain

$$\frac{d(\rho J + \tilde{\rho} \tilde{J})}{dt} \geq \rho \int_{\Omega} v_z^2 \, d\mathbf{x} + \tilde{\rho} \int_{\Omega} \tilde{v}_z^2 \, d\mathbf{x} + f_1(t), \quad (11)$$

$$\frac{d\tilde{J}}{dt} = \int_{\Omega} \tilde{v}_z^2 \, d\mathbf{x} + f_2(t), \quad (12)$$

where

$$\begin{aligned} J &= \int_{\Omega} (\mathbf{v} \mathbf{u}) \, d\mathbf{x}, & \tilde{J} &= \int_{\Omega} (\tilde{\mathbf{v}} \mathbf{u}) \, d\mathbf{x}, \\ f_1(t) &= g(t) + \rho \nu h(t) + \tilde{\rho} \tilde{\nu} \tilde{h}(t), & f_2(t) &= G(t) + \tilde{\nu} \tilde{h}(t), \\ G(t) &= -\frac{1}{\tilde{\rho}} \int_0^R \int_0^{2\pi} r L P(r, \varphi, 0) \, dr \, d\varphi. \end{aligned}$$

Further, the estimation proved in [16] for $\lambda \in (0, 3)$ is written down as

$$\frac{(3 - \lambda)^2}{L^{(6-\lambda)}} J^2 \leq 2 \int_{\Omega} \tilde{v}_z^2 \, d\mathbf{x}.$$

From (11), (12) one can obtain a system of differential inequalities

$$\frac{dJ}{dt} \geq k^2 J^2 + f(t), \quad \frac{d\tilde{J}}{dt} \geq k^2 \tilde{J}^2 + f_2(t),$$

where

$$f(t) = \frac{f_1(t) - \tilde{\rho}f_2(t)}{\rho}, \quad k^2 = \frac{(3 - \lambda)^2}{2L^{(6-\lambda)}}.$$

Thus, according to [11, 16], we have established the validity of the following

Theorem. *The classical solution of problem (1)–(6) does not globally exist if the following conditions are fulfilled:*

- 1) *let $f(t), f_2(t) \geq 0$, then under the conditions $J(0), \tilde{J}(0) > 0$, the lower estimations are valid:*

$$\begin{aligned} J(t) &\geq \frac{J(0)}{1 - J(0)k^2t}, & J(0) &= \int_{\Omega} \mathbf{v}_0(\mathbf{x})\mathbf{u} \, d\mathbf{x}, \\ \tilde{J}(t) &\geq \frac{\tilde{J}(0)}{1 - \tilde{J}(0)k^2t}, & \tilde{J}(0) &= \int_{\Omega} \tilde{\mathbf{v}}_0(\mathbf{x})\mathbf{u} \, d\mathbf{x}, \end{aligned}$$

and there is an estimation for the time of destruction:

$$T_{\infty} \leq \frac{1}{k^2} \min\left(\frac{1}{J(0)}, \frac{1}{\tilde{J}(0)}\right);$$

- 2) *let $f(t) \geq a^2 > 0, f_2(t) \geq \tilde{a}^2 > 0$, then*

$$\begin{aligned} J(t) &\geq \frac{a}{k} \tan(akt + c_0), & c_0 &= \arctan\left(\frac{kJ(0)}{a}\right), \\ \tilde{J}(t) &\geq \frac{\tilde{a}}{k} \tan(\tilde{a}kt + \tilde{c}_0), & \tilde{c}_0 &= \arctan\left(\frac{k\tilde{J}(0)}{\tilde{a}}\right), \end{aligned}$$

and the estimation for the time of destruction is

$$T_{\infty} \leq \frac{1}{k} \min\left(\frac{\pi/2 - c_0}{a}, \frac{\pi/2 - \tilde{c}_0}{\tilde{a}}\right);$$

- 3) *let $f(t) \geq -a^2, f_2(t) \geq -\tilde{a}^2$, then under the conditions $kJ(0) > |a|, k\tilde{J}(0) > |\tilde{a}|$ the lower estimations are valid:*

$$\begin{aligned} J(t) &\geq \frac{a}{k} \frac{1 + c_0 e^{2akt}}{1 - c_0 e^{2akt}}, & c_0 &= \frac{kJ(0) - a}{kJ(0) + a}, \\ \tilde{J}(t) &\geq \frac{\tilde{a}}{k} \frac{1 + \tilde{c}_0 e^{2\tilde{a}kt}}{1 - \tilde{c}_0 e^{2\tilde{a}kt}}, & \tilde{c}_0 &= \frac{k\tilde{J}(0) - \tilde{a}}{k\tilde{J}(0) + \tilde{a}}, \end{aligned}$$

and the estimation for the time of destruction is

$$T_{\infty} \leq \frac{1}{2k} \min\left(\frac{1}{a} \ln \frac{kJ(0) + a}{kJ(0) - a}, \frac{1}{\tilde{a}} \ln \frac{k\tilde{J}(0) + \tilde{a}}{k\tilde{J}(0) - \tilde{a}}\right).$$

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